11. 11   Guidance function

Embedded Ethernet setting	
<AUF>=1	
C081-C096	Device name 1-16
C610	Emb Eth. IP setting mode
C611-C614	Emb Eth. IP address setting value
C615-C618	Emb Eth. Subnet mask setting value
C619-C622	Emb Eth. Default gateway setting value
C629-C632	Emb Eth. IP address monitor
C633-C636	Emb Eth. Subnet mask monitor
C637-C640	Emb Eth. Default gateway monitor
Preset speed operation	
<AUF>=2	
CMOd	Run command select
FMOd	Frequency command select
ACC	Acceleration time 1
dEC	Deceleration time 1
FH	Maximum frequency
UL	Upper limit frequency
Sr1-Sr7	Preset speed 1-7
F111-F116	Terminal xx function
F287-F294	Preset speed 8-15
Analog frequency command	
<AUF>=3	
CMOd	Command mode selection
FMOd	Frequency mode selection
ACC	Acceleration time 1
dEC	Deceleration time 1
FH	Maximum frequency
UL	Upper limit frequency
LL	Lower limit frequency
F201	RR point 1 input value
F202	RR point 1 frequency
F203	RR point 2 input value
F204	RR point 2 frequency
F216	II point 1 input value
F217	II point 1 frequency
F218	II point 2 input value
F219	II point 2 frequency

Motor 1,2 switching	
<AUF>=4	
vL	Base frequency
vLv	Base frequency voltage 1
vb	Manual torque boost
tHrA	Motor overload protection current 1
ACC	Acceleration time 1
dEC	Deceleration time 1
F111-F116	Terminal xx function
F170	Base frequency 2
F171	Base frequency voltage 2
F172	Manual torque boost 2
F182	Motor overload protection current 2
F185	Stall prevention level 2
F415	Motor rated current
F500	Acceleration time 2
F501	Deceleration time 2
F601	Stall prevention level 1
Motor parameter	
<AUF>=5	
Pt	V/f pattern
vL	Base frequency
vLv	Base frequency voltage 1
F405	Motor rated capacity
F415	Motor rated current
F417	Motor rated speed
F400	Offline auto-tuning
PM motor parameter	
<AUF>=6	
Pt	Motor control type
vL	Motor base frequency
vLv	Motor nominal voltage
F400	Auto tuning
F402	Automatic torque boost
F405	Motor rated capacity
F415	Motor nominal current
F417	Motor nominal speed
F458	Current control P gain
F460	Speed loop P gain
F461	Speed loop I gain
F462	Load inertia
F910	Step-out detection current
F911	Step-out detection time
F912	Auto tune Lq axis
F913	Auto tune Ld axis
F914	Current stall prevention frequency
F915	Starting method
F916	Id current at starting
F917	Lq ratio at 100% load
F918	Lq ratio at 200% load
F919	Reluctance torque ratio

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